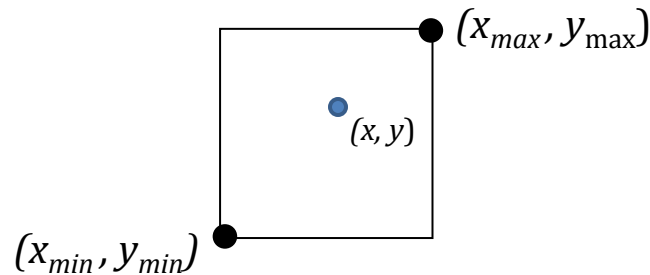


Clipping

Viewports and Algorithms

Line Clipping

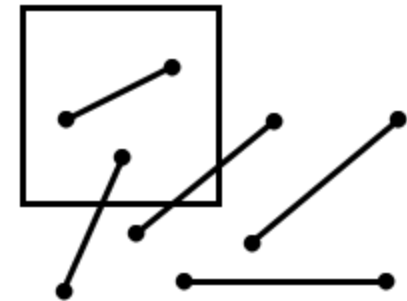
▶ Clipping endpoints



▶ $x_{min} < x < x_{max}$ **and** $y_{min} < y < y_{max}$ \Rightarrow point inside

▶ Endpoint analysis for lines:

- ▶ if both endpoints in , do “trivial acceptance”
- ▶ if one endpoint inside, one outside, must clip
- ▶ if both endpoints out, don’t know



- ▶ Brute force clip: solve simultaneous equations using $y = mx + b$ for line and four clip edges
 - ▶ slope-intercept formula handles infinite lines only
 - ▶ doesn’t handle vertical lines

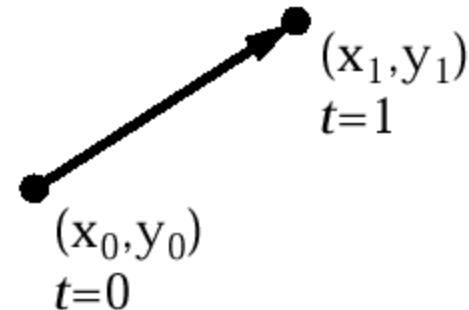
Parametric Line Formulation For Clipping

- ▶ Parametric form for line segment

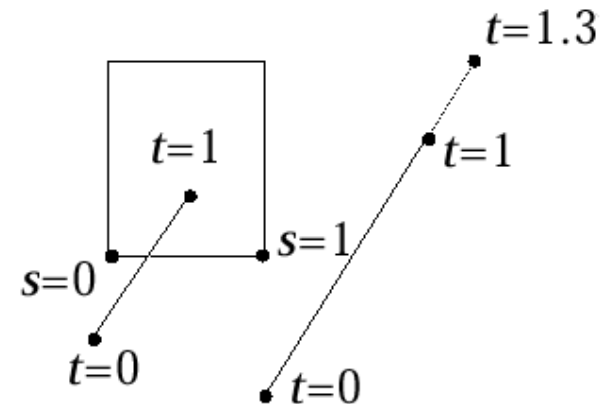
$$X = x_0 + t(x_1 - x_0) \quad 0 \leq t \leq 1$$

$$Y = y_0 + t(y_1 - y_0)$$

$$P(t) = P_0 + t(P_1 - P_0)$$

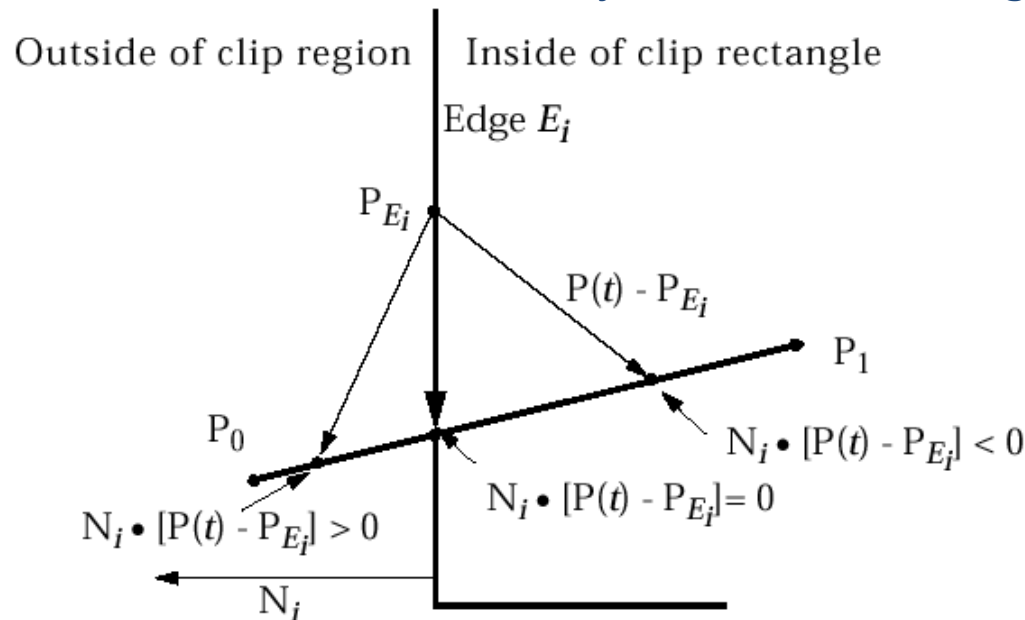


- ▶ Line in bounding area if parametric variables s_{edge} and t_{line} both in $[0,1]$ for intersection point between an edge and a line
 - ▶ Slow, must intersect lines with all edges



Cyrus-Beck/Liang-Barsky Parametric Line Clipping (1/3)

- ▶ Use parametric line formulation: $P(t) = P_0 + (P_1 - P_0)t$
- ▶ Determine where line intersects the infinite line formed by each clip rectangle edge
 - ▶ solve for t multiple times depending on the number of clip edges crossed
 - ▶ decide which of these intersections actually occur on the rectangle



- ▶ For P_{E_i} : use any point on edge E_i

Cyrus-Beck/Liang-Barsky Parametric Line Clipping (2/3)

- ▶ Now solve for the value of t at the intersection of $P_0 P_1$ with the edge E_i :

$$N_i \cdot [P(t) - P_{E_i}] = 0$$

- ▶ First, substitute for $P(t)$:

$$N_i \cdot [P_0 + (P_1 - P_0)t - P_{E_i}] = 0$$

- ▶ Next, group terms and distribute dot product:

$$N_i \cdot [P_0 - P_{E_i}] + N_i \cdot [P_1 - P_0]t = 0$$

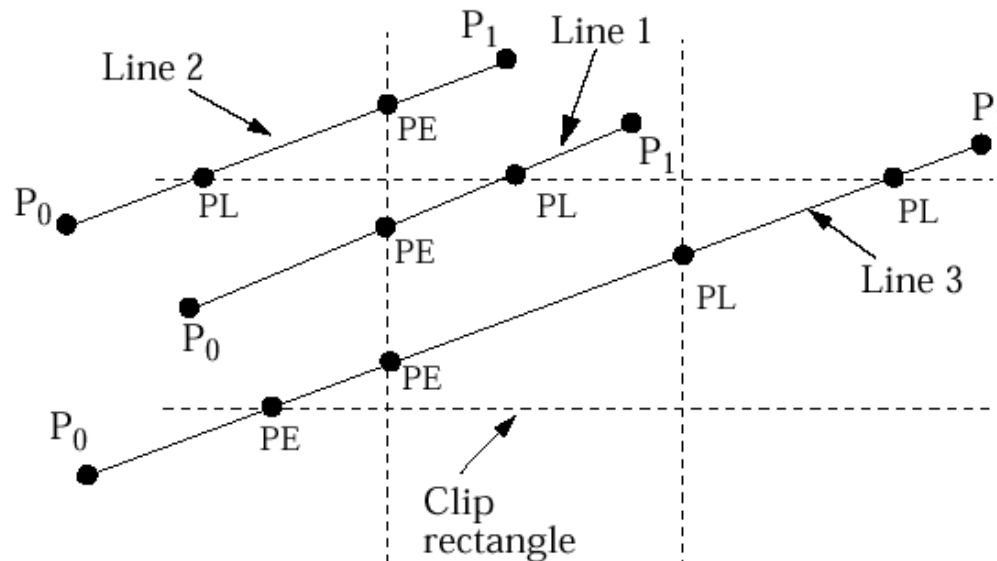
- ▶ Let D be the vector from P_0 to $P_1 = (P_1 - P_0)$, and solve for t :

$$t = \frac{N_i \cdot [P_0 - P_{E_i}]}{-N_i \cdot D}$$

- ▶ note that this gives a valid value of t only if the denominator of the expression is nonzero.
- ▶ For this to be true, it must be the case that:
 - ▶ $N_i \neq 0$ (that is, the normal should not be 0; this could occur only as a mistake)
 - ▶ $D \neq 0$ (that is, $P_1 \neq P_0$)
 - ▶ $N_i \cdot D \neq 0$ (edge E_i and line D are not parallel; if they are, no intersection).
- ▶ The algorithm checks these conditions.

Cyrus-Beck/Liang-Barsky Parametric Line Clipping (3/3)

- ▶ Eliminate t 's outside $[0,1]$ on the line
- ▶ Which remaining t 's produce interior intersections?
- ▶ Can't just take the innermost t values!



- ▶ Move from P_0 to P_1 ; for a given edge, just before crossing:
 - ▶ if $N_i \cdot D < 0 \Rightarrow$ Potentially Entering (PE); if $N_i \cdot D > 0 \Rightarrow$ Potentially Leaving (PL)
- ▶ Pick inner PE/PL pair: t_E for P_{PE} with max t , t_L for P_{PL} with min t , and $t_E > 0, t_L < 1$
- ▶ If $t_L < t_E$, no intersection

Cyrus-Beck/ Liang-Barsky Line Clipping Algorithm

```
Pre-calculate  $N_i$  and select  $P_{E_i}$  for each edge;  
for each line segment to be clipped  
  if  $P_1 = P_0$  then line is degenerate so clip as a point;  
  else  
    begin  
       $t_E = 0$ ;  $t_L = 1$ ;  
      for each candidate intersection with a clip edge  
        if  $N_i \cdot D \neq 0$  then {Ignore edges parallel to line}  
          begin  
            calculate  $t$ ; {of line and clip edge intersection}  
            use sign of  $N_i \cdot D$  to categorize as PE or PL;  
            if PE then  $t_E = \max(t_E, t)$ ;  
            if PL then  $t_L = \min(t_L, t)$ ;  
          end  
      if  $t_E > t_L$  then return nil  
      else return  $P(t_E)$  and  $P(t_L)$  as true clip intersections  
    end
```

Parametric Line Clipping for Upright Clip Rectangle (1/2)

- ▶ $D = P_1 - P_0 = (x_1 - x_0, y_1 - y_0)$
- ▶ Leave P_{E_i} as an arbitrary point on clip edge: it's a free variable and drops out

Calculations for Parametric Line Clipping Algorithm

Clip Edge _i	Normal N _i	P _{E_i}	P ₀ -P _{E_i}	$t = \frac{N_i \bullet (P_0 - P_{E_i})}{-N_i \bullet D}$
left: x = x _{min}	(-1,0)	(x _{min} , y)	(x ₀ - x _{min} , y ₀ - y)	$\frac{-(x_0 - x_{\min})}{(x_1 - x_0)}$
right: x = x _{max}	(1,0)	(x _{max} , y)	(x ₀ - x _{max} , y ₀ - y)	$\frac{-(x_0 - x_{\max})}{(x_1 - x_0)}$
bottom: y = y _{min}	(0,-1)	(x, y _{min})	(x ₀ - x, y ₀ - y _{min})	$\frac{-(y_0 - y_{\min})}{(y_1 - y_0)}$
top: y = y _{max}	(0,1)	(x, y _{max})	(x ₀ - x, y ₀ - y _{max})	$\frac{-(y_0 - y_{\max})}{(y_1 - y_0)}$

Parametric Line Clipping for Upright Clip Rectangle (2/2)

- ▶ Examine t :
 - ▶ numerator is just the directed distance to an edge; sign corresponds to OC
 - ▶ denominator is just the horizontal or vertical projection of the line, dx or dy ; sign determines PE or PL for a given edge
 - ▶ ratio is constant of proportionality: “how far over” from P_0 to P_1 intersection is relative to dx or dy